


iit **RECS** **Object properties can also be coded in terms of motor primitives**

- Position of objects can be coded in terms of the action required to reach it
- Trajectory of objects can be coded in terms of "collision trajectory" (which body part is going to hit)
- Shape/Size can be coded in terms of "grasp type" (small is whatever can be grasped with a pinch grasp)



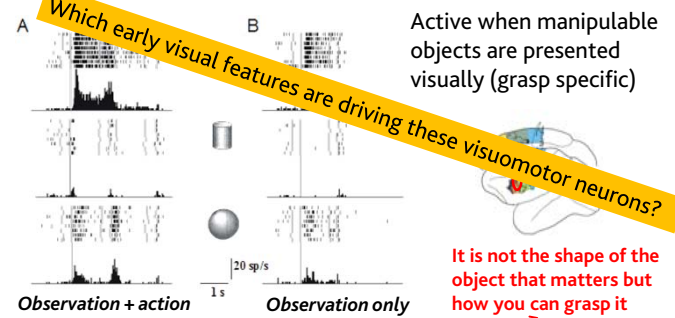
...small like this...

Robotics, Brain & Cognitive Sciences | Giulio Sandini

iit **RECS** **...canonical neurons in F5 representing visual properties of objects in motor terms**

Which early visual features are driving these visuomotor neurons?

Active when manipulable objects are presented visually (grasp specific)



Observation + action | Observation only

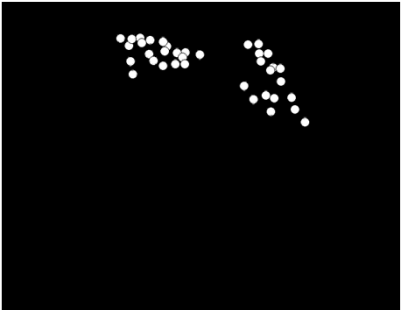
It is not the shape of the object that matters but how you can grasp it

From: Fadiga, L., L. Fogassi, V. Gallese, and G. Rizzolatti, *Visuomotor Neurons: ambiguity of the discharge or "motor" Perception?* International Journal of Psychophysiology, 2000. 35: p. 165-177.

Robotics, Brain & Cognitive Sciences | Giulio Sandini

iit **RECS** **Recognize an object without the object (shape from action)**

- How relevant is "action" in recognizing objects?
- Can the visual system exploit the view of haptic exploration to extract shape information of the explored object?




Study done with Francesco Campanella

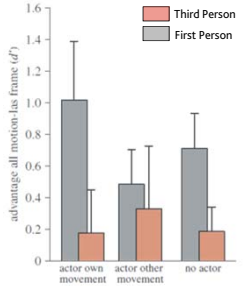
Robotics, Brain & Cognitive Sciences | Giulio Sandini

iit **RECS** **Size information and reaching**

human ability to extract some intrinsic object features, such as shape and size, from a visually presented reach-to-grasp movement.



Size is coded in the action to reach (and point of view matters)



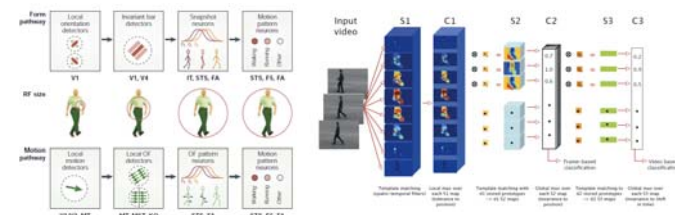
Condition	Third Person (d ²)	First Person (d ²)
actor own movement	~0.2	~1.0
actor other movement	~0.35	~0.5
no actor	~0.2	~0.7

Campanella Sandini, Morrone, Proc. R. Soc. B, 2010

Robotics, Brain & Cognitive Sciences | Giulio Sandini

iit RBCCS Modelling the Recognition of Biological Motion

Hierarchical models exploring the relationship between the ventral and the dorsal streams

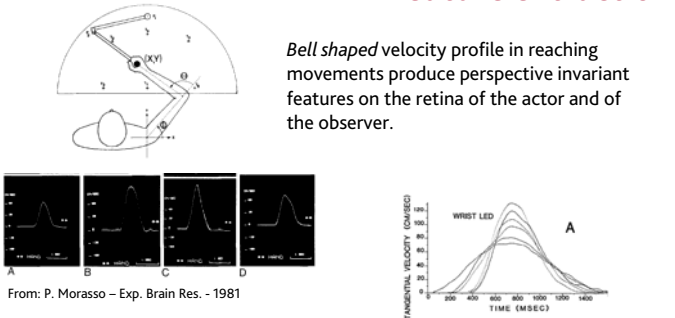


Jhuang , Serre, Wolf and Poggio- ICCV 2007

Giese & Poggio 2003

Robotics, Brain & Cognitive Sciences Giulio Sandini

iit RBCCS How can we exploit the regularities of human motion to "tune" early visual feature extraction?



Bell shaped velocity profile in reaching movements produce perspective invariant features on the retina of the actor and of the observer.

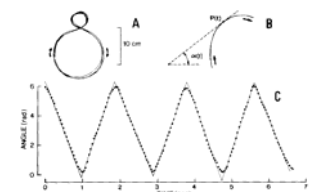
From: P. Morasso – Exp. Brain Res. - 1981

From: Atkeson & Hollerbach – J. Neuroscience 1985

Also: (Morasso 1981 , Morasso Mussa-Ivaldi 1982, Abend, Bizzi, Morasso, 1982)

Robotics, Brain & Cognitive Sciences Giulio Sandini

iit RBCCS Laquaniti's "2/3" Power Law



Isogony Principle: In drawing movements, equal angles are described in equal times (angular velocity tends to remain constant when the radius of curvature changes).
Viviani & Terzuolo 1982.

From: Laquaniti, Terzuolo, Viviani – Acta Psychologica - 1983

In rhythmic drawing movements, Laquaniti et. al. noted a power law relationship with proportionality constant k between the angular velocity $a(t)$ of the hand and the curvature of the trajectory path $c(t)$:

$$a(t) = k c(t)^{2/3}$$

Robotics, Brain & Cognitive Sciences Giulio Sandini

iit RBCCS "Human Motion Features" that could be exploited to *tune* early visual processes

- Regularity of velocity profile
- Position and time of changes of curvature (for segmentation)
- Relation between trajectory's curvature and velocity (e.g. 2/3 power law)
- Local rigidity (invariance of distance between joints)
- Common motion (not equal velocity but equal "visuo-motor pattern" – e.g. clouds of points with similar velocity profile or oscillations).
- Influence of gravity on trajectory.
- ...

Robotics, Brain & Cognitive Sciences Giulio Sandini

Questions for a possible discussion

- How can "motor knowledge" and the regularities of motor control be exploited to design/tune/learn how to compute early visual features?
- Is "looking at one's own body" a useful method to learn such features?
- How far can we go with only "bottom-up", feed forward models to explain human movement perception?
- What is innate and what is learned (and how)?

Thanks!